

# **METRICS PROJECT**

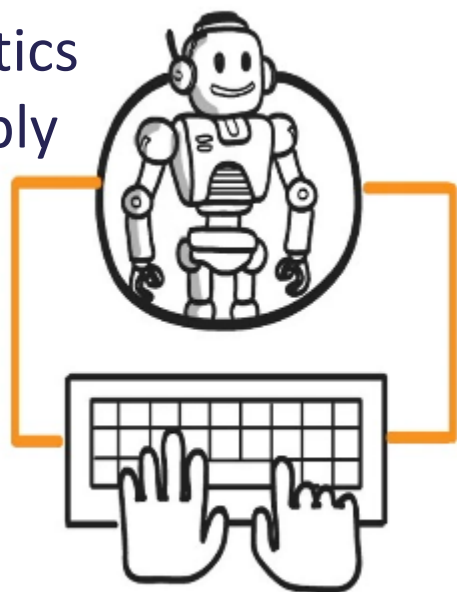
**Metrology-grade robotics  
competitions:**

Healthcare  
Inspection and Maintenance  
Agri-food  
Agile production

**Agnes DELABORDE, project n°871252  
coordinator**

# MATCHING SUPPLY AND DEMAND IN AI AND ROBOTICS THROUGH COMPETITIONS

AI and robotics supply



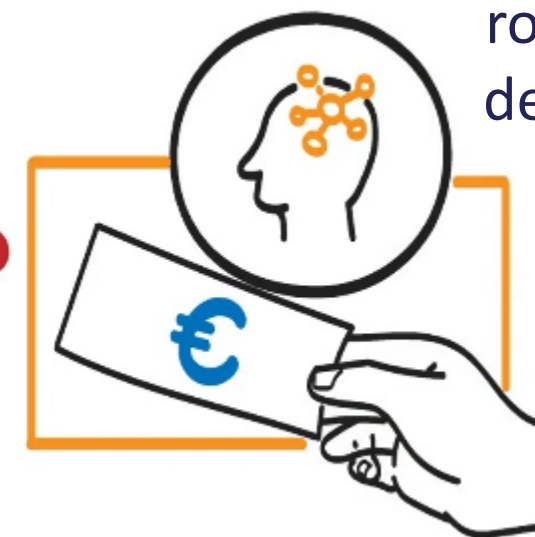
Black-box, non convex, evolute systems



Need: evaluation of AI and Robotics



AI and robotics demand



Trustworthy and efficient functionalities

# METRICS OBJECTIVES

1

Development of the Evaluation Framework

Evaluation framework based on **metrological principles** ensuring repeatable measurements and reproducible experiments

2

Organization of the 4 competitions

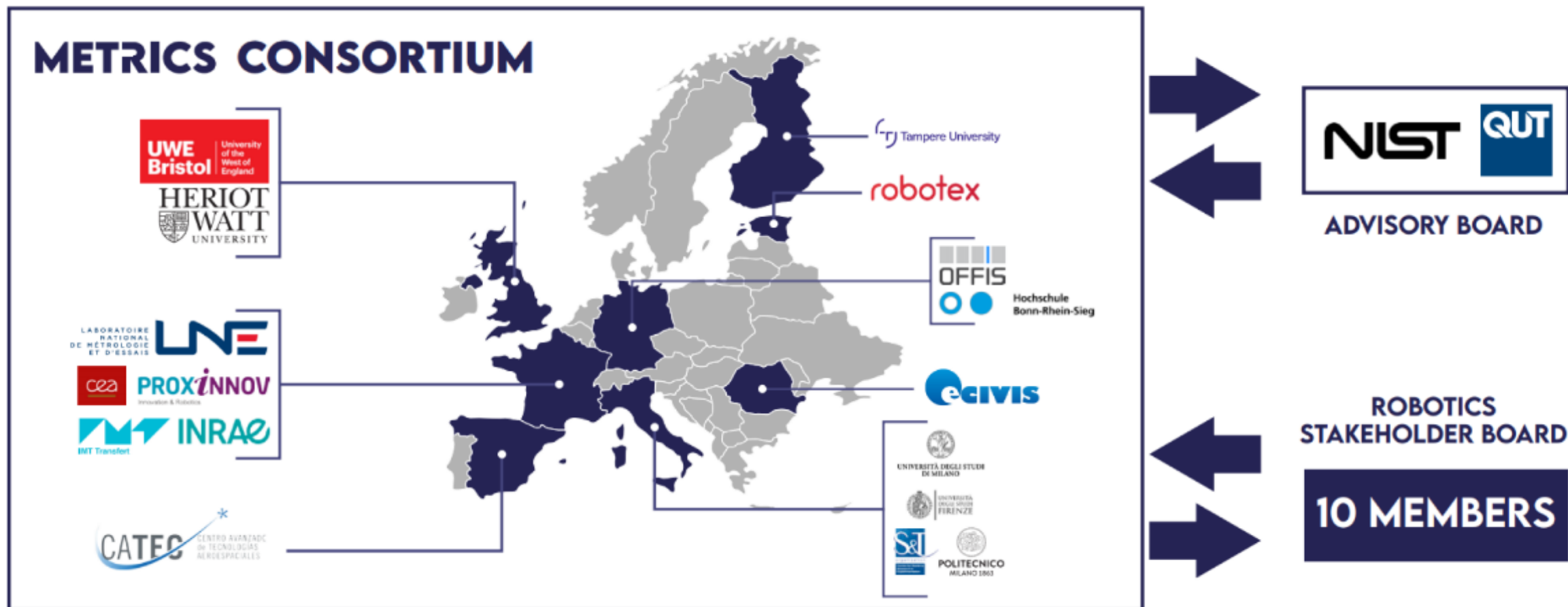
Combination of evaluations of **AI modules and entire robots**



3

Consolidation of the European robotics and AI community

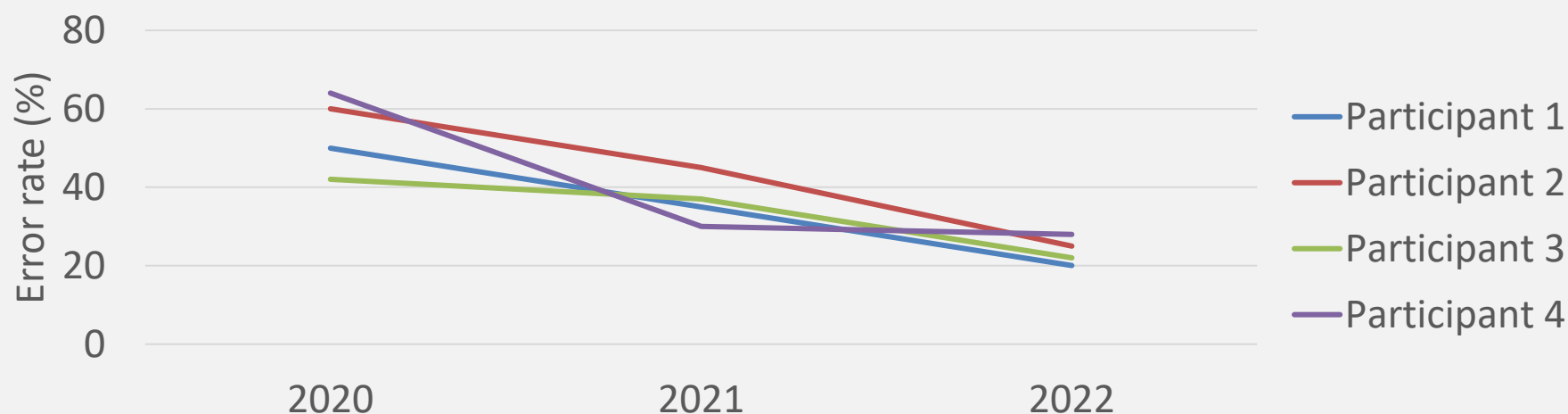
Collaborations with **DIH and external sponsors** to ensure industrial relevance



METRICS consortium relies on the collaboration of **17 partners from 8 EU countries** (Estonia, Finland, France, Germany, Italy, Romania, Spain, United Kingdom), which will contribute to strengthening the European AI and robotics communities, including in EU Widening countries

# EVALUATION CAMPAIGNS ORGANISATION

- **Dry-run:** First year campaigns aiming to validate the evaluation plan.



# COMPETITION ORGANISATION

- **Field Campaign:** Evaluate robot capabilities on a physical testbed.
- **Cascade Campaign:** Evaluate software capabilities on a dataset acquired during the Field Campaign.

# FIELD AND CASCADE EVALUATION CAMPAIGNS

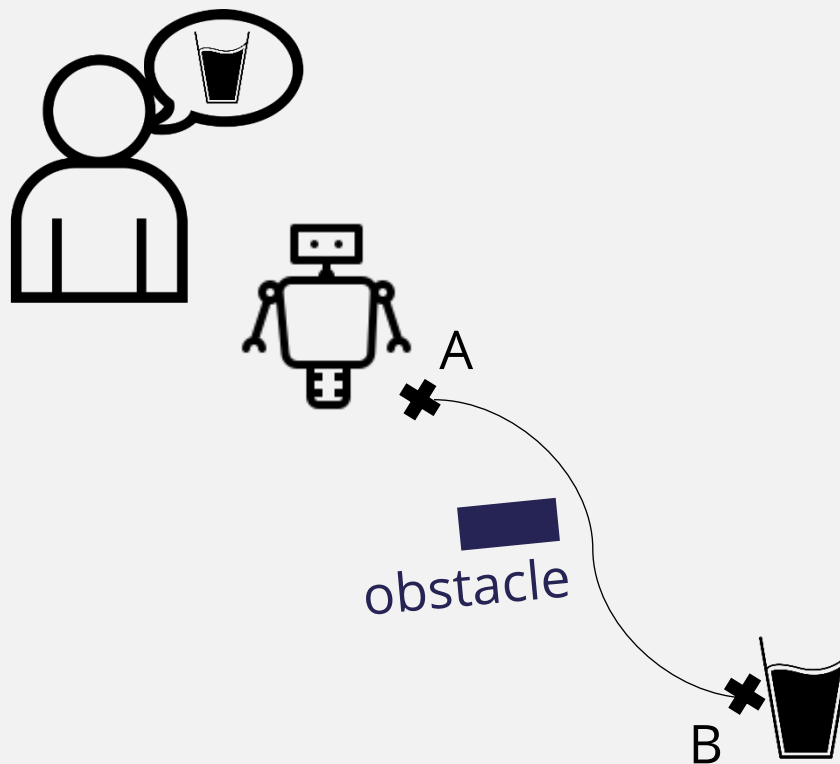
- The data used to evaluate the AI algorithms of the robots during the cascade evaluation is the one which is collected during the field evaluation



# FUNCTIONALITY AND TASK BENCHMARKS

## Task benchmarks (TBM)

TBM1 : To fetch for a glass of water when asked



## Functionality benchmarks (FBM)

FBM-1 : To understand fetching orders

FBM-2 : To detect obstacles

...

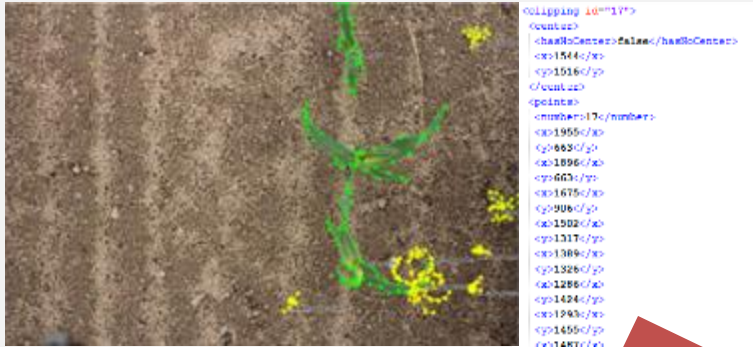
FBM-N : To grab a drink



# EVALUATION METHOD



Acquisition of images by the 4 evaluated robots



References: human annotations



Crop

Hypotheses : outputs from detection systems

(illustrations from ROSE Challenge - <http://challenge-rose.fr>)

Metric:

$$EGER = \frac{\sum_{k=1}^N C_k + FP_k + FN_k}{\sum_{k=1}^N R_k}$$

- Comparison**
1. Mapping
  2. Calculation of the error rate

# METRICS COMPETITIONS



**HEART-MET**  
Healthcare

## Assistive robots

1. Assess activity state
2. Item delivery
3. Area coverage
4. Prepare drink
5. Receive and transport drink



**RAMI**  
Inspection and  
maintenance

## Inspection autonomous robots

1. Underwater: pipeline area inspection and intervention
2. Aerial: punctual and repetitive inspection in difficult access areas



**ACRE**  
Agri-food

## Weeding robots

1. Intra-row weeding
2. Crop mapping



**ADAPT**  
Agile production

## Collaborative assembly robots

1. Collaborative programming for assembly
2. Collaborative assembly of complex parts

# HOW TO GET INVOLVED?

## As a participant:

- **What:** take part in one of the METRICS competitions by registering your technological solution to the corresponding evaluation campaigns (a robot for field evaluations and/or an AI algorithm for cascade evaluations).
- **Why:** take advantage, free of charge, of the evaluation tools made available by the consortium, test your system, position it in relation to those of the other participants and set up new collaborations.
- **How:** contact the coordinator of the corresponding competition (e.g. [acre@metricsproject.eu](mailto:acre@metricsproject.eu) for the agri-food competition, [im@metricsproject.eu](mailto:im@metricsproject.eu) for the I&M competition, etc.).

## As a sponsor:

- **What:** help us drive the competition through sponsorship (cash or in-kind contribution) as well as active involvement in the definition of the scenarios, evaluation criteria and judging of the competitions.
- **Why:** a unique opportunity to shape the competition challenges, rules and evaluation criteria to make them meaningful to your business current and future needs in robotics.
- **How:** contact the METRICS coordinator at [info@metricsproject.eu](mailto:info@metricsproject.eu).

# THANK YOU

[www.metricsproject.eu](http://www.metricsproject.eu) | [info@metricsproject.eu](mailto:info@metricsproject.eu)

